PUMP SHAFT, ADJUSTING NUT, AND
LOCKING SCREWS ARE NOT
FURNISHED WITH MOTOR

EO

AG
CD
AF
BV
BE
BB
AK
BD

AA SIZE
CONDUIT

45°
AC
AB

P
XO
BF
4 HOLES
AJ

DIMENSIONS ARE IN INCHES AND MILLIMETERS

UNITS	P [2]	AG	AJ	AK +.005	BB MIN	BE	BF	BV	CD	EO	XO
IN	23.75	42.69	14.750	13.500	.25	.75	.69	18.13	36.94	5.50	24.13
MM	603	1084	374.65	342.90	6	19	18	461	938	140	613

FRAME	CONDUIT BOX MATERIAL	UNITS	AA	AB	AC	AF
400	STEEL	IN	3.00	16.97	12.69	3.38
		MM		431	322	86
	CAST IRON	IN	3 NPT	17.75	13.38	4.63
		MM		451	340	118

FRAME	UNITS	BD MAX
404, 405TP	IN	16.50
	MM	419
404, 405TPA	IN	20.00
	MM	508

1: ALL ROUGH DIMENSIONS MAY VARY BY .25" DUE TO
   CASTING AND/OR FABRICATION VARIATIONS.
2: LARGEST MOTOR WIDTH.
3: TOLERANCES SHOWN ARE IN INCHES ONLY.
4: CONDUIT BOX OPENING MAY BE LOCATED IN STEPS
   OF 90° REGARDLESS OF LOCATION. STANDARD AS
   SHOWN WITH CONDUIT OPENING DOWN.

TOLERANCES	
FACE RUNOUT	.007 T.I.R.
PERMISSIBLE ECCENTRICITY OF MOUNTING RABBET	.007 T.I.R.

09-2293/B

Nidec Motor Corporation
St. Louis, Missouri

ISSUED BY
R. KING
APPROVED BY
M. TREJO

IHP_DP_NMCA (MAR-2011) SOLIDEDGE

NAMEPLATE DATA

CATALOG NUMBER:	HO125V2SLG		NAMEPLATE PART #:	422707-005

MODEL	DT80	FR	405TP	TYPE	RUSI	ENCL	WPI

SHAFT END BRG	6212-J - QTY 1	OPP END BRG	7222 BEM - QTY 1

PH	3	MAX AMB	40 C	ID#	

INSUL CLASS	F	Asm. Pos.		DUTY	CONT

HP	125		RPM	1785		HP			RPM		
VOLTS	460					VOLTS					
FL AMPS	142.0					FL AMPS					
SF AMPS	164.0					SF AMPS					

SF	1.15	DESIGN	B	CODE	G
NEMA NOM EFFICIENCY	95.4	NOM PF	86.8	KiloWatt	93.250
GUARANTEED EFFICIENCY	94.5	MAX KVAR		HZ	60

SF		DESIGN		CODE	
NEMA NOM EFFICIENCY		NOM PF			
GUARANTEED EFFICIENCY		MAX KVAR		HZ	

HAZARDOUS LOCATION DATA (IF APPLICABLE):

DIVISION		CLASS I		GROUP I	
TEMP CODE		CLASS II		GROUP II	

VFD DATA (IF APPLICABLE):

VOLTS	460	
AMPS	149.1	

TORQUE 1	368.1LB-FT	TORQUE 2	
VFD LOAD TYPE 1	VT/PWM	VFD LOAD TYPE 2	
VFD HERTZ RANGE 1	6-60	VFD HERTZ RANGE 2	
VFD SPEED RANGE 1	180-1800	VFD SPEED RANGE 2	

SERVICE FACTOR	1.00	FL SLIP	
NO. POLES		MAGNETIZING AMPS	
VECTOR MAX RPM		Encoder PPR	
Radians / Seconds		Encoder Volts	

TEAO DATA (IF APPLICABLE):

HP (AIR OVER)		HP (AIR OVER M/S)		RPM (AIR OVER)		RPM (AIR OVER M/S)	
FPM AIR VELOCITY		FPM AIR VELOCITY M/S		FPM AIR VELOCITY SEC			

Quotation Bill of Material

Item	Qty	Product Information
1	1	ACH550-BCR-157A-4+F267

ACH550 6-Pulse drive package rated UL (NEMA) Type 1. Provided with Main Input Circuit Breaker and E-Clipse Bypass (Box). Rated for 157 amps (125 HP) at 480 VAC Three Phase. 5% input impedance. Rated 100 kA SCCR.

Included Options:
[+F267]: Service Switch

Submittal Schedule

This schedule includes the products supplied as part of this submittal.

Schedule			Motor Data[1]			Drive Data			
Item	Qty	Tag	HP	FLA	Volts	Product ID	HP	Amps	Volts
1	1		125	156	460 VAC	ACH550-BCR-157A-4+F267	125	157	480 VAC
Notes:		1.	AC motor data is per National Electrical Code Table 430.250 for typical motors used in most applications. It is provided as typical data only. DC motor data is per typical industry standards. Actual motor data may vary						

Submittal Schedule Details for

Item	Tag / Equipment ID	Product ID
1		ACH550-BCR-157A-4+F267

Item Description
Input Voltage: 480 VAC Three Phase
Rated Output Current: 157A
Enclosure: UL (NEMA) Type 1
Nominal Horsepower: 125 HP
Frame Size: R6
Input Disconnecting Means: Circuit Breaker
Bypass: E-Clipse Bypass (Box)
Input Impedance: 5%
Short Circuit Current Rating: 100 kA
Communication Protocols: Johnson Controls N2, Siemens Building Technologies FLN (P1), Modbus RTU, BACnet (MS/TP)
Other Options: [+F267]: Service Switch

Drive Input Fuse Ratings	
Fuse Class	**Amps (600 V)**
225A	Class T

Wire Size Capacities of Power Terminals		
Input Wiring	**Output Wiring**	**Ground Wiring**
#3/0 124 in-lbs	300 MCM 301 in-lbs	2 X #3/0 250 in-lbs

Dimensions and Weights			
Height *in* *(mm)*	**Width** *in* *(mm)*	**Depth** *in* *(mm)*	**Weight** *lbs* *(kg)*
47.7 (1212)	28.1 (713)	19.0 (483)	359 (163)

Heat Dissipation & Airflow Requirements			
Power Losses		**Airflow**	
BTU/Hr	**Watts**	**CFM**	**CM/Hr**
7,877	2310	238	405

ACH550 Product Overview

Description

The ACH550 series is a microprocessor based Pulse Width Modulated (PWM) adjustable speed AC drive. The ACH550 drive takes advantage of sophisticated microprocessor control and advanced IGBT power switching technology to deliver high-performance control of AC motors for a wide range of HVAC applications.

With drives ranging from 1 to 550 HP, the ACH550 series features a universal full graphic interface that "speaks" to the operator in plain English phrases, greatly simplifying set-up, operation, and fault diagnosis. The ACH550 is also programmable in fourteen other languages.

Each ACH550 drive comes equipped with an extensive library of pre-programmed HVAC application macros which, at a touch of a button, allow rapid configuration of inputs, outputs, and performance parameters for specific HVAC applications to maximize convenience and minimize start-up time. The ACH550 series can handle the most demanding commercial applications in an efficient, dependable, and economic manner.

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ACH550 Standard Features

UL, cUL labeled and CE marked, BTL listed
EMI/RFI Filter (1st Environment, Restricted Distribution)
Seismic Certificate of Compliance in accordance with
    IBC 2000 referencing ASCE 7-98 and ICC AC156
    IBC 2003 referencing ASCE 7-02 and ICC AC156
    IBC 2006 referencing ASCE 7-05 and ICC AC156
    IBC 2009 referencing ASCE 7-05 and ICC AC156
Start-Up Assistants
Maintenance Assistants
Diagnostic Assistants
Real Time Clock (Includes Day, Date and Time)
Operator Panel Parameter Backup (read/write)
Full Graphic and Multilingual Display
  for Operator Control, Parameter Set-Up and Operating
  Data Display:
      Output Frequency (Hz) / Motor Speed (RPM)
      Motor Current
      Calculated Energy Savings ($, kWh/MWh, CO_2)
      Calculated % Motor Torque
      Calculated Motor Power (kW)
      DC Bus Voltage
      Output Voltage
      Heatsink Temperature
      Elapsed Time Meter (reset-able)
      KWh (reset-able)
      Input / Output Terminal Monitor
      PID Actual Value (Feedback) & Error
      Fault Text
      Warning Text
      Three (3) Scalable Process Variable Displays
      User Definable Engineering Units
Two (2) Programmable Analog Inputs
Six (6) Programmable Digital Inputs
Two (2) Programmable Analog Outputs
Up to six (6) Programmable Relay Outputs (Three (3) Standard)
Adjustable Filters on Analog Inputs and Outputs
Mathematical Functions on Analog Reference Signals
All Control Inputs Isolated from Ground and Power
Four (4) Resident Serial Communication Protocols
    BACnet (MS/TP)
    Johnson Controls N2
    Siemens Building Technologies FLN (P1)
    Modbus RTU
Input Speed Signals
    Current 0 (4) to 20 mA
    Voltage 0 (2) to 10 VDC
    Increase/Decrease Reference Contacts (Floating Point)
    Serial Communications
Start/Stop
    2 Wire (Dry Contact Closure)
    3 Wire (Momentary Contact)
    Application of Input Power
    Application of Reference Signal (PID Sleep/Wake-Up)
    Serial Communications
Start Functions
    Ramp
      Flying Start
      Pre-magnetization (DC Brake) on Start
    Automatic Torque Boost
    Automatic Torque Boost with Flying Start
    Auto Restart (Reset) – Customer Selectable and
    Adjustable
Stop Functions
    Ramp or Coast to Stop
    Emergency Stop
    DC Braking / Hold at Stop
    Flux Braking
Accel/Decel
    Two (2) sets of Independently Ramps
    Linear or Adjustable 'S' Curve Accel/Decel Ramps

HVAC Specific Application Macros
Separate Safeties (2) and Run Permissive Inputs
Damper Control
Override Input (Fire Mode)
Timer Functions
    Four (4) Daily Start/Stop Time Periods
    Four (4) Weekly Start/Stop Time Periods
    Four Timers for Collecting Time Periods and
      Overrides
Seven (7) Preset Speeds
Supervision Functions
Adjustable Current Limit
Electronic Reverse
Automatic Extended Power Loss Ride Through (Selectable)
Programmable Maximum Frequency to 500 Hz
PID Control
    Two (2) Integral Independent Programmable PID
      Setpoint Controllers (Process and External)
    External Selection between Two (2) Sets of Process
      PID Controller Parameters
    PID Sleep/Wake-Up
Motor Control Features
    Scalar (V/Hz) and Vector Modes of Motor Control
    V/Hz Shapes
      Linear
      Squared
    Energy Optimization
    IR Compensation
    Slip Compensation
    Three (3) Critical Frequency Lockout Bands
Preprogrammed Protection Circuits
    Overcurrent
    Short Circuit
    Ground Fault
    Overvoltage
    Undervoltage
      Input Phase Loss
    Output Device (IGBT) Overtemperature
    Adjustable Current Limit Regulator
    UL508C approved Electronic Motor Overload (I^2T)
Programmable Fault Functions for Protection Include
    Loss of Analog Input
    Panel Loss
    External Fault
    Motor Thermal Protection
    Stall
    Underload
    Motor Phase Loss
    Ground Fault
Input Impedance
    5% Equivalent Impedance with Internal Reactor(s)
      Patented Swinging Choke Design for Superior
      Harmonic Mitigation (R1…R6 Frames)
    3% Equivalent Impedance (R8 Frame)

OPTIONAL FEATURES
3 Relay Extension Module (OREL-01)
115/230 V Digital input Interface Card (OHDI-01)
Fieldbus Adapter Modules
    LonWorks
    BACnet IP to MS/TP Router
    Profibus
    DeviceNet
    Ethernet
    ControlNet
DriveWindow Light Start-up, Operation, Programming
  and Diagnostic Tool
Fan Replacement Kit

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ACH550 Specifications

Input Connection

Input Voltage (U_1)..208…240 VAC 3-phase +/-10%
                                                                       208…240 VAC 1-phase +/-10%
                                                                       380…480 VAC 3-phase +/-10%
                                                                       500…600 VAC 3-phase +/-10%
Frequency: ....48 - 63 Hz
Line Limitations: ....Max +/-3% of nominal phase to phase input voltage
Fundamental Power Factor (cos φ):.........................0.98 at nominal load
Connection: ....U_1, V_1, W_1 (U_1, V_1, 1-phase)

Output (Motor) Connection

Output Voltage: ....0 to U_1, 3-phase symmetrical, U_2 at the field weakening point
Output Frequency: ....-500 to 500 Hz
Frequency Resolution: ....0.01 Hz
Continuous Output Current:
     Variable Torque: ....1.0 * I_{2N} (Nominal rated output current, Variable Torque)
Short Term Overload Capacity:
     Variable Torque:.....................................1.1 * I_{2N}, (1 min/10 min)
Peak Overload Capacity:
     Variable Torque:.....................................1.35 * I_{2N}, (2 sec/1 min)
Base Motor Frequency Range: ....10 to 500 Hz
Switching Frequency: ....1, 4, 8 or 12 kHz
Acceleration Time: ....0.1 to 1800 s
Deceleration Time: ....0.1 to 1800 s
Efficiency: ....0.98 at nominal power level
Short Circuit Withstand Rating: ....100,000 AIC (UL)
Connection: ....U_2, V_2, W_2

Enclosure

Style: ....UL (NEMA) Type 1, Type 12, or Type 3R

Agency Approval

Listing and Compliance:.......................................UL, cUL, CE

Ambient Conditions, Operation

Air Temperature: ....-15^0 to 40^{0}C (5^0 to 104^{0}F), above 40^{0}C the maximum output
                                                                       current is de-rated 1% for every additional 1^{0}C (up to 50^{0}C
                                                                       (122^{0}F) maximum limit.
Relative Humidity:..5 to 95%, no condensation allowed, maximum relative
                                                                       humidity is 60% in the presence of corrosive gasses
Contamination Levels:
     IEC:...60721-3-1, 60721-3-2 and 60721-3-3
     Chemical Gasses: ....3C1 and 3C2
     Solid Particles: 3S2
Installation Site Altitude:......................................0 to 1000 m (3300 ft) above sea level. At sites over 1000 m
                                                                       (3300 ft) above sea level, the maximum power is de-rated
                                                                       1% for every additional 100 m (330 ft). If the installation site
                                                                       is higher than 2000 m (6600 ft) above sea level, please
                                                                       contact your local ABB distributor or representative for further
                                                                       information
Vibration:..Max 3.0 mm (0.12 in) 2 to 9 Hz, Max 10 m/s^2 (33 ft/s^2) 9 to
                                                                       200 Hz sinusoidal
                                                                       Seismic Certified referencing IBC 2000, 2003, 2006 and 2009

Ambient Conditions, Storage and Transportation (in Protective Shipping Package)

Air Temperature: ....-40^0 to 70^{0}C (-40^0 to 158^{0}F)
Relative Humidity:..Less than 95%, no condensation allowed
Atmospheric Pressure:..60 to 106 kPa (8.7 to 15.4 PSI)
Vibration:..In accordance with ISTA 1A and 1B specifications
                                                                       Max 3.5 mm (0.14 in) 2 to 9 Hz, Max 15 m/s^2 (49 ft/s^2) 9 to
                                                                       200 Hz sinusoidal
Shock (IEC 60086-2-29):.....................................Max 100 m/s^2 (330 ft/s^2) 11 ms
Free Fall: ....R1:   76 cm (30 in)
                                                                       R2:   61 cm (24 in)
                                                                       R3:   46 cm (18 in)
                                                                       R4:   31 cm (12 in)
                                                                       R5 & 6: 25 cm (10 in)

Cooling Information

Cooling Method:...Integral fan(s)
Power Loss: ....Approximately 3% of rated power

ACH550 Specifications (continued)

Analog Inputs
Quantity...Two (2) programmable
Voltage Reference: ....0 (2) to 10 V, 312kOhm, single ended
Current Reference: ....0 (4) to 20 mA, 100Ohm, single ended
Potentiometer:...10 VDC, 10 mA (1K to 10KOhms)
Input Updating Time...8 ms
Terminal Block Size ....$2.3mm^2$ / 14AWG

Reference Power Supply
Reference Voltage ....+10 VDC, 1% at 25^0C (77^0F)
Maximum Load ....10 mA
Applicable Potentiometer......................................1 kOhm to 10 kOhm
Terminal Block Size ....$2.3mm^2$ / 14AWG

Analog Outputs
Quantity...Two (2) programmable current outputs
Signal Level...0 (4) to 20 mA
Accuracy ....+/- 1% full scale range at 25^0C (77^0F)
Maximum Load Impedance...................................500 Ohms
Output Updating Time..2 ms
Terminal Block Size ....$2.3mm^2$ / 14AWG

Digital Inputs
Quantity...Six (6) programmable digital inputs
Isolation ....Isolated as one group
Signal Level...24 VDC, (10V Logic 0)
Input Current ....15 mA at 24 VDC
Input Updating Time: ....4 ms
Terminal Block Size ....$2.3mm^2$ / 14AWG

Internal Power Supply
Primary Use...Internal supply for digital inputs
Voltage:...+24 VDC, max 250 mA
Maximum Current: ....250 mA
Protection: ....Short circuit protected

Relay Outputs
Quantity...Three (3) programmable relay (Form C) outputs
Switching Capacity:..8 A at 24 VDC or 250 VAC, 0.4 A at 120 VDC
Max Continuous Current: ....2A RMS
Contact Material: ....Silver Cadmium Oxide (AgCdO)
Isolation Test Voltage ....4 kVAC, 1 minute
Output Updating Time...12 ms
Terminal Block Size ....$2.3mm^2$ / 14AWG

Protections
Single Phase..Protected (input & output)
Overcurrent Trip Limit: ....3.5 x I_{2N} instantaneous
Adjustable Current Regulation Limit: ....1.1 x I_{2N} (RMS) max.
Overvoltage Trip Limit: ....1.30 x U_N
Undervoltage Trip Limit: ....0.65 x U_N
Overtemperature (Heatsink):................................+115°C (+239°F)
Auxiliary Voltage:..Short Circuit Protected
Ground Fault: ....Protected
Short Circuit:..Protected
Microprocessor fault: ....Protected
Motor Stall Protection: ....Protected
Motor Overtemperature Protection (I_2t): ....Protected
Input Power Loss of Phase: ....Protected
Loss of Reference:...Protected
Short Circuit Current Rating: ....100,000 RMS symmetrical Amperes
Input Line Impedance:...Swinging choke 5% equivalent R1-R6, 3% equivalent R8

U_1 = Input Voltage U_N = Nominal Motor Voltage
U_2 = Output Voltage f_N = Nominal Motor Frequency
P_N = Power – Normal Duty (HP) I_{2N} = Nominal Motor Current – Normal Duty

Specifications are subject to change without notice. Please consult the factory when specifications are critical.

ACH550 Control Panel

The ACH550 Control Panel is a multifunction control panel with full graphic LCD display and multiple language capability. The control panel can be connected to and detached from the ACH550 at any time. The panel can be used to upload and copy parameters to other ACH550 drives.
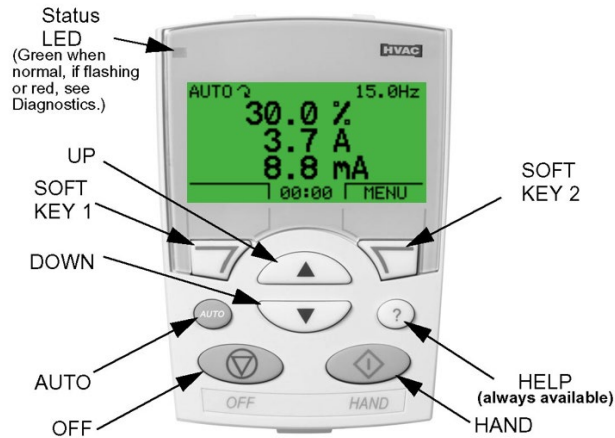
Run Indication and Shaft Direction ↻ located in upper left corner of display.

Control Panel Display	Significance
Rotating arrow (clockwise or counterclockwise)	Drive is running and at set point Shaft direction is forward or reverse
Rotating arrow blinking	Drive is operating but not at setpoint
Stationary arrow	Drive is stopped

LED Indicators
The green LED indicates that the power is on and the drive is operating normally. The red LED indicates a fault. A blinking green LED indicates an alarm condition. A blinking red LED indicates a fault that requires power to be cycled off and on to reset the drive.

Fault Indications
The ACH550 Control Panel can display over 20 alarm and fault messages. The last fault and previous faults (1 to 9) are retained in memory. The last fault and previous faults (1 & 2) also record important diagnostic information to assist in troubleshooting. Most faults can be reset by pressing the RESET key (Soft Key 1).

Parameters
Application specific parameters are immediately accessible through a selection of start-up "Assistants". A complete list of parameters is also available grouped by function in approximately 33 menu groups. One of the basic menu functions can be used to display the complete list of changed parameters.

Real Time Clock
The Operator Control Panel includes a real time clock which provides Day, Date and Time information, displayed in a choice of formats. The real time clock has a 10 year battery back up and provides time and date stamping of drive faults and other events. The clock is also used by the ACH550s internal timer functions, providing an integral time clock for start/stop control as well as other control operations.

Control Modes

When the HAND key is pressed, the drive starts and pressing the UP/DOWN keys can modify the reference frequency. The HAND (keypad) control mode is indicated.

When the OFF key is pressed, the drive stops and the OFF control mode is indicated.

When the AUTO key is pressed, the AUTO control mode is indicated. The drive can be started and stopped using whichever remote start/stop command has been configured, a contact closure applied to the start/stop input, a serial communication command or a process feedback signal. In AUTO mode the drive speed is typically controlled by the external speed reference input or by the PID controller.

If the HAND key is pressed while the drive is running in the AUTO control mode, the drive continues to run without changing speed, but ceases to respond to external input or PID speed reference changes. (Bumpless transfer) Pressing the UP/DOWN keys can modify the reference frequency.

If the AUTO key is pressed while the drive is running in the HAND control mode and an external start command is present, the drive continues to run and follows the acceleration or deceleration control ramp to the speed set by the external input or PID speed reference. (Bumpless transfer)

Cable Connections

Terminal	Description	Note
U1, V1, W1	3~ power supply input	Use of 1~ supply requires 50% derate of output current and is applicable for 208 to 240 VAC operation only.
PE / GND	Protective Ground	Follow local rules for cable size.
U2, V2, W2	Power output to motor	
Uc+, Uc-	DC bus	
X1 1 to 18	Control Wiring	Low voltage control – Use shielded cable
X1 19 to 27	Control Wiring	Low voltage or 115VAC
X1 28 to 32	Serial Communications	Use shielded cable

Follow local codes for cable size. To avoid electromagnetic interference, use separate metallic conduits for input power wiring, motor wiring, control and communications wiring. Keep these four classes of wiring separated in situations where the wiring is not enclosed in metallic conduit. Also, keep 115VAC control wiring separated from low voltage control wiring and power wiring.

Use shielded cable for control wiring.

Ampacity is based on the use of 60 °C rated power cable up to 100 Amps (75 °C over 100 Amps).

Refer to the included tables for current ratings, fuse recommendations and maximum wire size capacities and tightening torques for the terminals. The ACH550 is suitable for use on a circuit capable of delivering not more than 100,000 RMS symmetrical amperes, 480 V maximum. The ACH550 has an electronic motor protection feature that complies with the requirements of the National Electric Code (NEC). When this feature is selected and properly adjusted. Additional overload protection is not required unless more than one motor is connected to the drive or unless additional protection is required by applicable safety regulations.

For CE installation requirements, see ABB publication CE-US-02 "CE Council Directives and Variable Speed Drives." Contact your local ABB representative for specific IEC installation instructions.

ACH550 Control Terminals - Main I/O Terminal X1

X1	Identification	Description	
1	SCR	Terminal for signal cable screen. (Connected internally to chassis ground.)	
2	AI 1	Analog input channel 1, programmable. Default[2] = External reference Resolution 0.1 % accuracy ±1 %. 0 (4) - 20 mA (R_i = 312 kΩ) (J1:AI1 ON) 0 (2) - 10 V (R_i = 100 Ω) (J1:AI1 OFF)	
3	AGND	Analog input common. (Connected internally to chassis ground through 1 MΩ)	
4	10 V	10 V/10 mA reference voltage output for analog input potentiometer, accuracy ±2 %. (1 k$\Omega \leq$ R $\leq$ 10 kΩ)	
5	AI 2	Analog input channel 2, programmable. Default[2] = PID Feedback Resolution 0.1 % accuracy ±1 %. 0 (4) - 20 mA (R_i = 312 kΩ) (J1:AI2 ON) 0 (2) - 10 V (R_i = 100 Ω) (J1:AI2 OFF)	
6	AGND	Analog input common. (Connected internally to chassis ground through 1 MΩ)	
7	AO1	Analog output channel 1, programmable. Default[2] = Output frequency 0 (4) - 20 mA (load < 500 Ω), accuracy ±3% full scale.	
8	AO2	Analog output channel 2, programmable. Default[2] = Output current 0 (4) - 20 mA (load < 500 Ω), accuracy ±3% full scale.	
9	AGND	Analog output common. Connected internally to chassis ground through 1 MΩ	
10	24 V	Auxiliary voltage output 24 V DC / 250 mA (Reference to AGND). Short circuit protected.	
11	GND	Common for digital input (DI) return signals.	
12	DCOM	Digital input circuit common for all digital inputs (DIs). Connected internally as floating.	
DI Configuration[1]		To activate a digital input, there must be $\geq$ +10 V (or $\leq$ -10 V) between that input and DCOM. The 24 V may be provided by the ACH550 (X1:10) or by an external 12-24 V source of either polarity.	
13	DI 1	Digital input 1, programmable. Default[2] = Start/Stop (AUTO mode) Activation starts the drive	
14	DI 2	Digital input 2, programmable. Default[2] = Not configured.	
15	DI 3	Digital input 3, programmable. Default[2] = Constant (Preset) speed. Activation selects constant speed 1	
16	DI 4	Digital input 4, programmable. Default[2] = Start enable 1 (safety interlock) Deactivation stops the drive.	
17	DI 5	Digital input 5, programmable. Default[2] = Not configured.	
18	DI 6	Digital input 5, programmable. Default[2] = Not configured.	
19	RO1C	Common	Relay output 1, programmable (Default[2] = Ready – 19 connected to 21). 12 - 250 V AC / 30 V DC, 10 mA - 2 A
20	RO1A	Normally Closed (NC)	
21	RO1B	Normally Open (NO)	
22	RO2C	Common	Relay output 2, programmable (Default[2] = Running - 22 connected to 24). 12 - 250 V AC / 30 V DC, 10 mA - 2 A
23	RO2A	Normally Closed (NC)	
24	RO2B	Normally Open (NO)	
25	RO3C	Common	Relay output 3, programmable (Default[2] = Fault (-1)[3] - 25 connected to 27). 12 - 250 V AC / 30 V DC, 10 mA - 2 A
26	RO3A	Normally Closed (NC)	
27	RO3B	Normally Open (NO)	
28	Screen	Terminal for signal cable screen. (Connected internally to chassis ground.)	
29	B	RS-485 Serial Communications Positive input connection	
30	A	RS-485 Serial Communications Negative input connection	
31	AGND	Analog input common. (Connected internally to chassis ground through 1 MΩ.)	
32	Screen	Terminal for signal cable screen. (Connected internally to chassis ground.)	

Notes: 1. Digital input impedance 1.5 kΩ. Maximum voltage for digital inputs is 30 V. Use multi-strand wire, size range: 20-16 AWG (0.5-1.5 mm^2)
2. Default values depend on the macro used. Values specified are for the HVAC default macro.
3. For fail-safe reasons, the Fault (-1) Relay signals a "Fault", when the ACH550 is powered down.

ACH550 with ABB E-Clipse bypass – Overview

ABB E-Clipse bypass Standard Features

- Door Interlocked Disconnect or Circuit Breaker
- English Language Back-Lit LCD Display
- Operator Control Panel
- LED Status Pilot Lights
- Smoke Control
- Override Mode
- Serial Communications
- 5 Programmable Relay Outputs (Form C)
- 100% Functionality with Drive Removed
- Programmable Auto Transfer to Bypass
- Plain English Safety Annunciation
- UL & cUL Listed
- Seismic Zone 4 Certified (IBC 2006)
- UL Type 1, Type 12 or Type 3R Enclosure
- Programmable Class 10, 20, or 30 OL
- Automatic Restart
- 24 Month Parts and Labor Warranty (with Certified Start-up)
- Two Contactor Bypass
- System Status Display
- Bypass Diagnostics Display
- Drive Exclusive Fast-Acting Fuses
- Electronic Motor Overload Protection
- Damper Control - VFD and Bypass Modes
- 6 Digital Inputs (5 programmable)
- Single Phase Protection in VFD & Bypass Mode
- Bullet Proof Contactor Protection
- Serial Communications Pass Through I/O
- Proof-of-Flow Indication & Action
- Conformal Coated Circuit Boards
- +30%; -35% Input Voltage Tolerance
- Run Permissive Circuit
- Supervisory Control
- UL Listed I^{2}T Electronic Overload
- UL Listed and tested 100,000 Ampere SCCR (VCR and BCR Units)

The ACH550 with ABB E-Clipse bypass is an ACH550 HVAC Drive in an integrated UL Type 1, UL Type 12 or NEMA 3R enclosure with a bypass motor starter. The ACH550 with ABB E-Clipse bypass provides an input disconnect switch or circuit breaker with door mounted and interlocked operator (padlockable in the OFF position), a bypass starter, electronic motor overload protection, a local programming and operator keypad with indicating lights, provisions for external control connections, and serial communications capability. Certain configurations (+F267) also provide a drive service switch.

UL Type 1 (NEMA 1) and UL Type 12 (NEMA 12) E-Clipse units are available from 1 to 100 HP at 208/240V, 1 to 400 HP at 480V, and 2 to 150 HP at 600V. UL Type 1 and UL Type 12 units are wall mounted from 1 to 200 HP and floor mounted from 250 to 550 HP. The operator keypad is mounted on the door of the enclosure.

For outdoor applications, UL Type 3R (NEMA 3R) E-Clipse unit are available from 1 to 100 HP at 208/240V, 1 to 200 HP at 480V and 2 to 150 HP at 600V. Construction is sheet steel with a tough powder coat paint finish for corrosion resistance. A thermostatically controlled space heater and thermostatic control of the force ventilated cooling system are standard. The operator keypads are mounted on the enclosure door and covered by a hinged panel.

The ACH550 with ABB E-Clipse bypass includes two contactors. One contactor is the bypass contactor, used to connect the motor directly to the incoming power line in the event that the ACH550 is out of service. The other contactor is the ACH550 output contactor that disconnects the ACH550 from the motor when the motor is operating in the Bypass mode. The drive output contactor and the bypass contactor are electrically interlocked to prevent "back feeding".

The ACH550 with ABB E-Clipse bypass is a microprocessor-controlled "intelligent" system which features programmable Class 20 or 30 overload curves, programmable underload (broken belt) and overload trip or indication. Also included as standard features are single-phase protection in bypass mode, programmable manual or automatic transfer to bypass, fireman's override, smoke control, damper control, no contactor chatter on brown-out power conditions and serial communications. Should a drive problem occur, fast acting fuses exclusive to the ACH550 drive path disconnect the drive from the line prior to clearing upstream branch circuit protection, maintaining bypass capability.

Damper Control Circuit (Run Permissive)

The damper control circuit closes a dry contact upon a start command to open a damper such as an outdoor air damper, fire damper, isolation damper, etc. before the motor is allowed to operate in drive mode or bypass mode regardless of the source of the run command. When the damper is fully open, a normally open dry contact from the damper end-switch closes and allows the motor to operate. Up to four dedicated inputs are provided for safety interlocks such as firestats, smoke detectors, etc.

The safety interlock inputs may also be linked to plain English keypad diagnostic indications to be displayed on the LCD. The unit may be set-up to display any of the following diagnostics upon opening of a digital input: Vibration Switch; Firestat; Freezestat; Over Pressure; Vibration Trip; Smoke Alarm; Safety Open; Low Suction; Start Enable; Run Enable; Damper End Switch; Valve Open Proof; or Pre-Lube Cycle. When any of these contacts open, the motor stops (in drive or bypass mode) and the damper is commanded to close. Although it is not a recommend sequence of operation, this run permissive circuit may also be controlled via serial communications.

Smoke Control and Override Modes

The ACH550 with ABB E-Clipse bypass has two Override modes of operation for critical control situations. The Smoke Control Override accepts a normally open dry contact that forces the motor to run in bypass and ignores all keypad inputs. In Smoke Control Override mode, the system acknowledges high priority digital inputs such as overpressure safeties and damper end-switch run permissive proofs, and disregards other, low priority digital inputs. See the attached sample wiring diagram for further details. Smoke Control Override (Override 1) response is not field programmable. The unit will go into smoke Override mode whenever DI6 is closed.

X2 E-Clipse Bypass Controller Input

Terminal	Function
1	
2	
3	
4	
5	(DI1) Start/Stop
6	(DI2) Run Enable
7	(DI3) High Priority Safeties
8	(DI4) Emergency Shutdown
9	(DI5) Low Priority Safeties
10	(DI6) Smoke Control
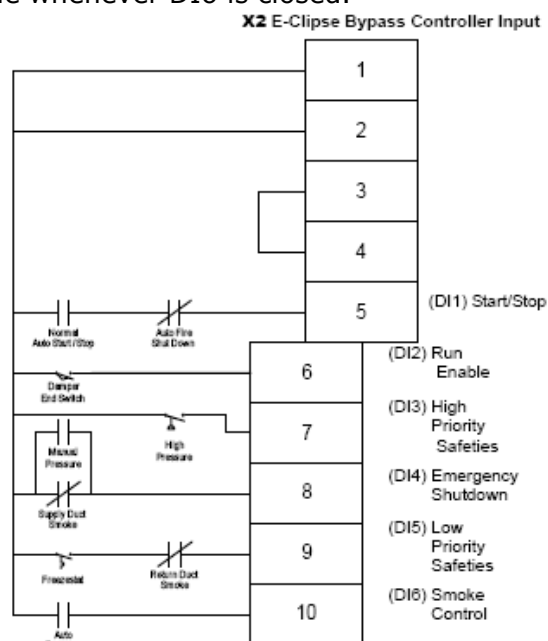
Normal Operation:
- Close Start/Stop (X2:5)
- Fan starts, assuming that X2: 6, 7, 8, and 9 are all closed

Emergency Shutdown:
- Open auto fire shutdown, unit stops

Smoke Control Mode:
- Close contact on X2:10
- Fan starts regardless of position of internal HOA switch and inputs X2:5 and X2:9
- Inputs X2:6, 7 and 8 followed
- Internal overloads followed

Typical Starter Wiring for a Smoke Control listed System Today:
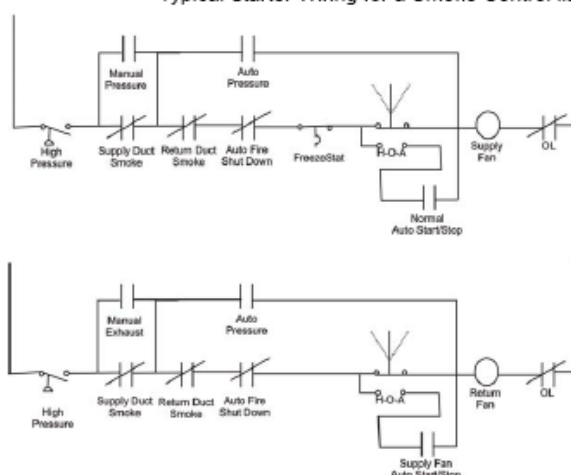
Notes:
1. Pressure cutouts, duct smoke detectors and auto shutdown are 2-pole.
2. Manual control also activates "auto control" relays.

The second mode, Override 2, is fully programmable. Override 2 default programming is designed for "Run to Destruction" operation.   However, the end user can program the unit to acknowledge some external inputs while ignoring others, ignore all external inputs or acknowledge all external inputs. This mode is fully programmable to allow the user to program the response of the unit to match his local AHJ.

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Serial communications

All ABB E-Clipse bypass units have the following Embedded Fieldbus (EFB) protocols included as standard: Modbus RTU; Johnson Controls N2; Siemens Building Technologies FLN (P1); and BACnet (MS/TP).

The ACH550 with ABB E-Clipse bypass has the ability to monitor VFD/Bypass mode of operation, the status of the bypass H-O-A switch, bypass fault and override status over serial communication. In addition, the user can monitor and / or control over 45 points of bypass information via the communications protocols. Serial communication capabilities include - bypass run-stop control; the ability to force the unit to bypass; and the ability to control all relay outputs. The DDC system can monitor bypass feedback such as, current (in amps), kilowatt hours (resettable), operating hours (resettable), and bypass logic board temperature. The DDC system is also capable of monitoring the bypass relay output status, and all digital input status'. All bypass diagnostic warning and fault information is transmitted over the serial communications bus. Remote system (drive or bypass) fault reset is possible.
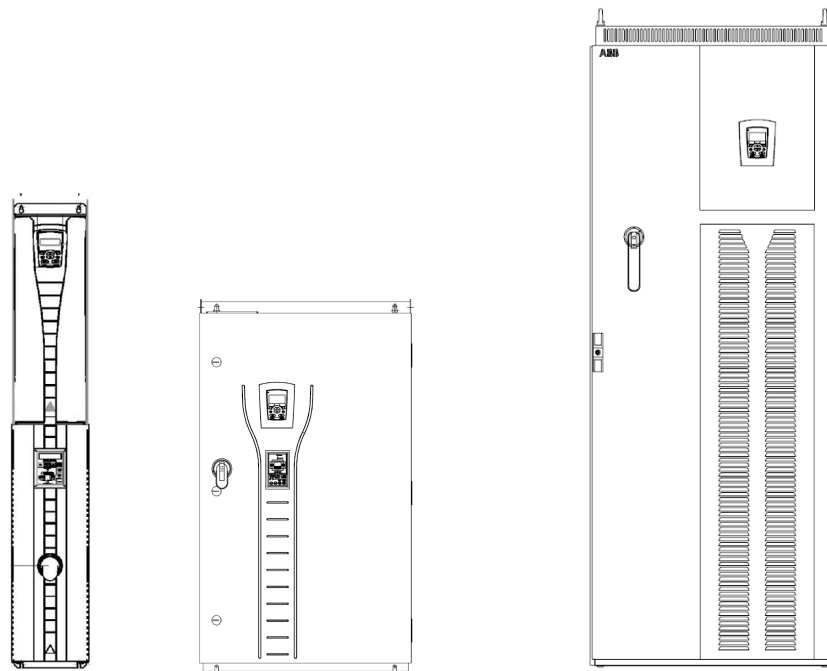
Vertical & Standard ABB E-Clipse bypass Exterior Views

ABB E-Clipse bypass Operator Control

ACH550 Control Panel

The ACH550 Control Panel is a keypad with an LCD unit that provides status indication and operator controls for the ACH550 drive. In normal operation with the ABB E-Clipse bypass, the ACH550 should be placed in the *Auto* mode of operation by pressing the *Auto* key on the ACH550 Control Panel. Refer to the *ACH550 User's Manual* for additional information on the ACH550 Control Panel and other aspects of ACH550 operation.

Bypass Control Keypad

The ABB E-Clipse bypass has a separate keypad with an LCD unit that provides status indication and programming of the system. This keypad is also used for selecting the *Drive* or *Bypass* mode of operation and manually starting and stopping the motor in the *Bypass* mode. The bypass keypad has LED indicating lights that indicate the status of both the bypass and the drive as well as an LCD display that provides programming, status and warning/fault indications.

The illustration below shows the bypass control keypad and identifies the keys and LED indicating lights.
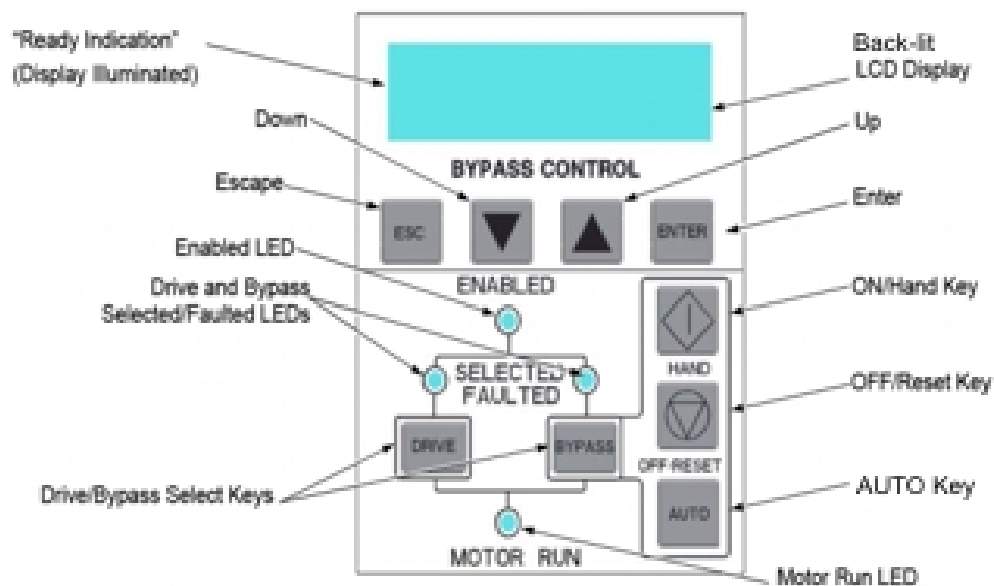
The functions of the various keys and LEDs are described in the following table.

Enabled LED	The *Enabled* LED is illuminated green under the following conditions: • Both the Safety Interlock(s) and Run Enable contacts are closed. • The Safety Interlock(s) contact are closed with no Start command present. The *Enable* LED flashes green if the Run Enable contact is open and when the Safety Interlock contact(s) are closed and a Start command is present. The Enable LED is illuminated red when the Safety Interlock contact(s) are open.
Drive Selected LED	The *Drive Selected* LED is illuminated green when the drive has been selected as the power source for the motor and no drive fault is present.
Bypass Selected LED	The *Bypass Selected* LED is illuminated green when the bypass has been selected as the power source for the motor and no bypass fault is present.
Motor Run LED	The *Motor Run* LED is illuminated green whenever the system is running. The *Motor Run* LED flashes green to indicate the system has been placed in an Override operating mode.
Drive Faulted LED	The *Drive Fault* LED is illuminated red when the bypass has lost its' communications link with the drive or when the motor or drive protection functions have shut down the drive.
Bypass Faulted LED	The *Bypass Faulted* LED is illuminated or flashes red when the motor or bypass protective functions have shut down the bypass.
Drive Key	The *Drive* Key selects the drive as the power source for the motor.
Bypass Key	The *Bypass* Key selects the bypass as the power source for the motor.
Auto Key	The *Auto* key selects the *Auto Start* contact or serial communications as the means for starting and stopping the motor in the bypass mode.
Off/Reset Key	The *Off/Reset* key may be used to manually stop the motor if the motor is running on bypass power. The *Off/Reset* Key also resets most bypass faults. It may take several minutes before the bypass can be reset after an overload trip. If a bypass fault condition is present, the second push of the *Off/Reset* key puts the bypass in the Off mode.
Hand Key	The *Hand* key can be used to manually start the motor when the bypass has been selected as the power source for the motor.
UP Key	Used to navigate through system programming steps.
Down Key	Used to navigate through system programming steps.

Control Modes

Drive mode

Under normal conditions the system is in the *Drive* mode. The ACH550 drive provides power to the motor and controls its speed. The source of the drive's start/stop and speed commands is determined by the *Auto* or *Hand* mode selection of the drive's keypad. Commands come from the control terminals or serial communications when the *Auto* mode has been selected or from the drive keypad when the *Hand* mode has been selected. The user can normally switch to the *Drive* mode by pressing the *Drive* key on the bypass keypad.

Bypass mode

In the *Bypass* mode, the motor is powered by AC line power through the bypass contactor. The source of the bypass start/stop commands is determined by the *Auto* or *Hand* mode selection of the bypass' keypad. Commands come from the control terminals or serial communications when the *Auto* mode has been selected or from the bypass keypad when the *Hand* mode has been selected. The user can normally switch to the *Bypass* mode by pressing the *Bypass* key on the bypass keypad.

Smoke Control mode

In the *Smoke Control (Override 1)* mode, the motor is powered by AC line power through the bypass contactor. The source of the Smoke Control command is DI 6 and is unaffected by external stop commands. The VFD Keypad and the Bypass Keypad will not accept user commands when the system is in Smoke Control mode (the keypad user inputs are disabled). The user can switch to the *Smoke Control* mode by closing the *Smoke Control* input contact (DI 6). When the *Smoke Control* input contact is closed, the system is forced to bypass and runs the motor. The Motor Run LED flashes green when the system is in override. While in *Smoke Control*, the system only responds to certain inputs. Normally when the *Smoke Control* input contact is switched from closed to open, the system returns to the operating mode that existed prior to entering *Smoke Control* and can once again be controlled using the *Drive* and *Bypass* keys. The exception to this is when the *Bypass Override (Override 2)* input contact is closed, in which case the system switches to *Bypass Override* operation.

Bypass Override mode

In the *Bypass Override (Override 2)* mode, the motor is powered by AC line power through the bypass contactor. The source of the start command is internal and unaffected by external stop commands. The VFD Keypad and the Bypass Keypad will not accept user commands when the system is in Bypass Override mode (the keypad user inputs are disabled). The user can switch to the *Bypass Override* mode by closing the *Bypass Override* input contact (DI 5-if programmed). When the *Bypass Override* input contact is closed, the system is forced to bypass and does not respond to the *Drive* and *Bypass* keys. The Motor Run LED flashes green when the system is in override. While in *Bypass Override* the system responds to bypass overloads and programmed faults. The system may be custom programmed to acknowledge or disregard certain faults, safeties and enables. The unit is default programmed to ignore all external safeties and run enables. See Group 17 for programmability of the digital input and fault functions. Normally when the *Bypass Override* input contact is switched from closed to open, the system switches to the *Drive* mode and can be controlled using the *Drive* and *Bypass* keys. The exception to this is when the *Smoke Control (Override 1)* input contact is closed, in which case the system remains in *Smoke Control* operation.

Hand mode

When the system is in the *Bypass* mode, the operator can manually start the motor by pressing the *Hand* key. The motor will run and the *Hand* LED will be illuminated green. In order to run the motor, the *Safety Interlock* and *Run Enable* contacts must be closed (green *Enable* LED) and any bypass fault must be reset.

Auto mode

In the *Auto* mode the bypass start/stop command comes from the *Start/Stop* input terminal on the bypass control board or from serial communications – if programmed. The *Auto* mode is selected by pressing the *Auto* key on the bypass keypad. The *Auto* LED is illuminated green when the bypass is in the *Auto* mode. If the system is in the *Bypass* mode, the motor will run across the line if the *Auto* mode is selected, the *Start/Stop, Safety Interlock* and *Run Enable* contacts are closed and any bypass fault is reset.

Off Mode

If the motor is running in the *Bypass* mode, the operator can manually stop the motor by pressing the *OFF* key. The *Motor Running* LED will go out. The motor can be restarted by pressing the *Hand* key or the bypass can be returned to the *Auto* mode by pressing the *Auto* key. If the system is in the *Drive* mode, pressing the *OFF* key will take the bypass out of the *Auto* mode, but will not affect motor operation from the drive. If the system is switched to the *Bypass* mode, a motor that is running will stop.

Programmable Relay Contact Outputs

The ABB E-Clipse bypass has five programmable relay outputs as standard. The default programming descriptions for these relay outputs is described below.

Bypass Not Faulted

The *Bypass Not Faulted* relay is energized during normal operation. The *Bypass Not Faulted* relay is de-energized when a bypass fault has occurred.

System Running

The *System Running* relay is energized when the ABB E-Clipse bypass System is running. The *System Running* relay provides an output when the motor is running whether powered by the ACH550 drive or the bypass.

System Started

The *System Started* relay is energized when the ABB E-Clipse bypass system is started. Three conditions must be met in order for the relay to energize. 1) a *Start* command must be present, 2) the *Safety Interlock* input contact must be closed and 3) there can be no fault present in the system. The *Start* command can come from the bypass control board terminal block, the ACH550 keypad, the bypass keypad, or serial communications depending on the operational mode selected. The *System Started* relay is ideal for use in damper actuator circuits, opening the dampers only under those conditions where the system is preparing to run the motor. The *System Started* relay will de-energize, closing the dampers if the safeties open, the system faults, or when a *Stop* command is issued.

Bypass Selected

Relay output four is factory default programmed for Bypass Selected. The relay will be energized anytime the user has placed the system in Bypass mode.

Bypass Auto

Relay Output five is factory default programmed for *Bypass Auto*. The relay will be energized anytime the user has placed the bypass in the Auto mode.

The complete list of programmable relay output functions follows:

0 = NOT SEL	10 = DRV NOT FLT	20 = BYP UNDERLD
1 = SYS READY	11 = DRIVE ALARM	21 = PCB OVERTMP
2 = SYS RUNNING	12 = OVERRIDE	22 = SYS UNDERLD
3 = SYS STARTED	13 = BYPASS HAND	23 = SYSTEM FLT
4 = BYPASS SEL	14 = BYPASS OFF	24 = SYS FLT/ALM
5 = BYPASS RUN	15 = BYPASS AUTO	25 = SYS EXT CTL
6 = BYPASS FLT	16 = COM CTRL	26 = SYS OVERLD
7 = BYP NOT FLT	17 = SYS ALARM	27 = CONTACT FLT
8 = BYPASS ALRM	18 = BYPASS FLT/ALM	
9 = DRIVE FAULT	19 = BYP OVERLD	

Cable Connections

The following illustrations show the ACH550 with ABB E-Clipse bypass cable connection points for the various enclosure styles. The illustrations indicate the location of input and output power connections as well as equipment and motor grounding connection points.

ACH550 drives are configured for wiring access from the bottom only on Vertical ABB E-Clipse bypass units and from the top only on Standard ABB E-Clipse bypass units. At least three separate metallic conduits are required, one for input power, one for output power to the motor and one for control signals.

All ABB E-Clipse bypass units provided with a circuit breaker input - VCR and BCR configurations have a panel short circuit current rating of 100,000 RMS symmetrical Amperes. Units provided with a disconnect input - VDR and BDR configurations require separate external low peak fuses (supplied by others) to obtain the 100,000 KAIC SCCR.
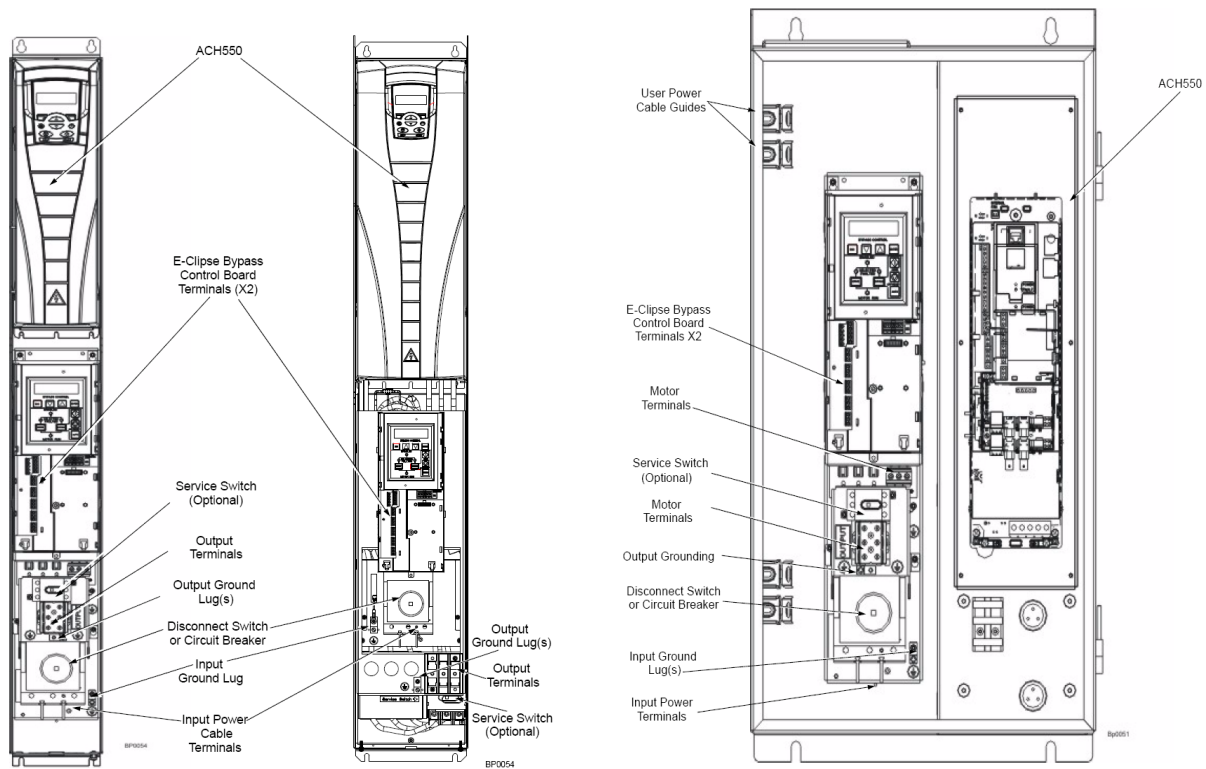
Terminal Sizes

Power and motor cable terminal sizes are shown in the *Submittal Schedule Details* and in the *Wire Size Capacities of Power Terminals* Table. The information provided is for connections to an input circuit breaker or disconnect switch, a motor terminal block, overload relay and ground lugs. The table also lists torque that should be applied when tightening the connections.

Protections

All ABB E-Clipse bypass units include the following protective features: single phase input and output; motor open phase; motor overload (UL Listed); stuck contactor; contactor coil open; undervoltage; motor underload (proof-of-flow / broken belt); serial communications loss; and overtemperature. All printed circuit boards are conformally coated as standard.

Internal Layout Drawings

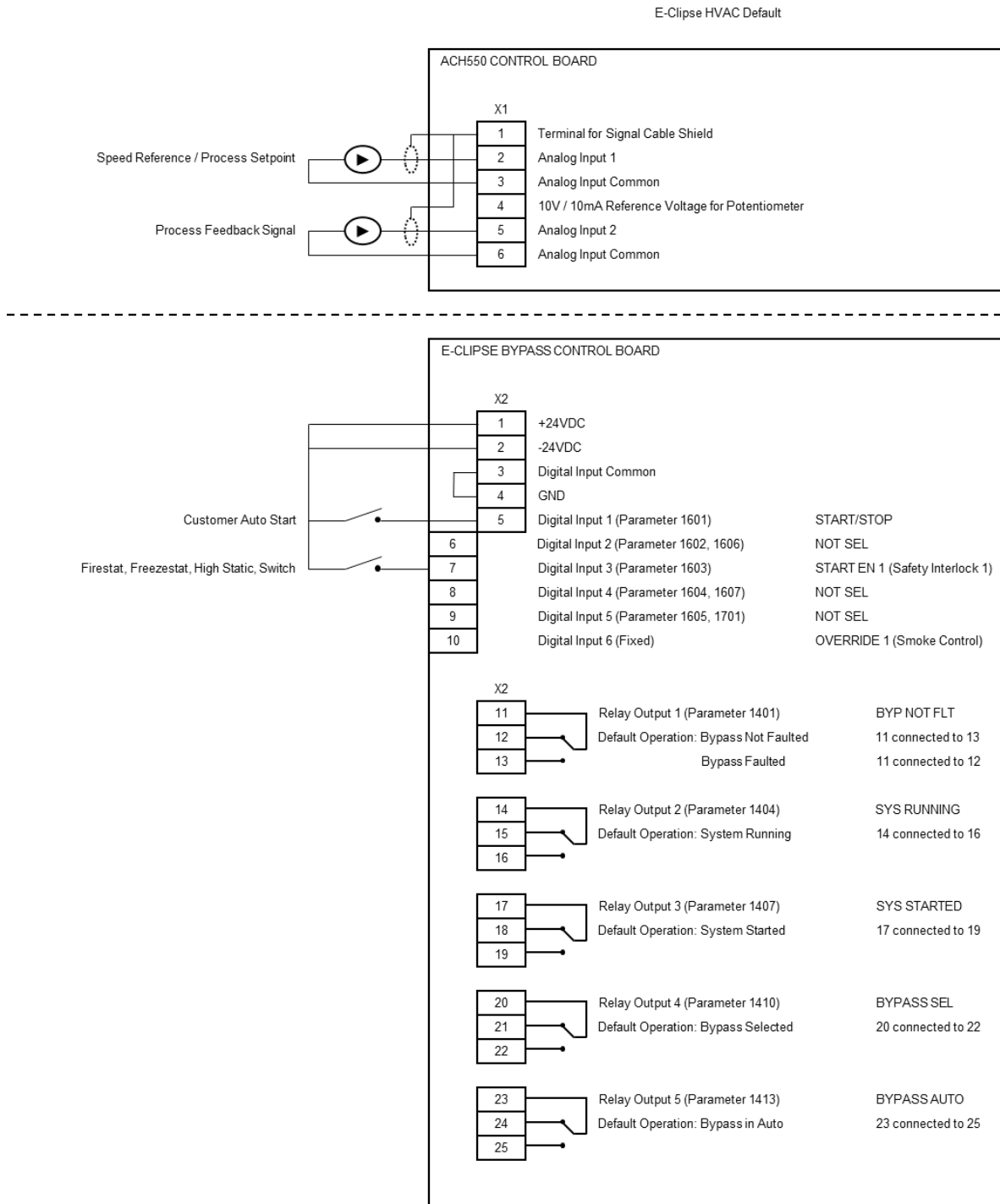Vertical ABB E-Clipse Bypass
(UL Type 1 / 12)

Standard Wall Mount ABB E-Clipse Bypass
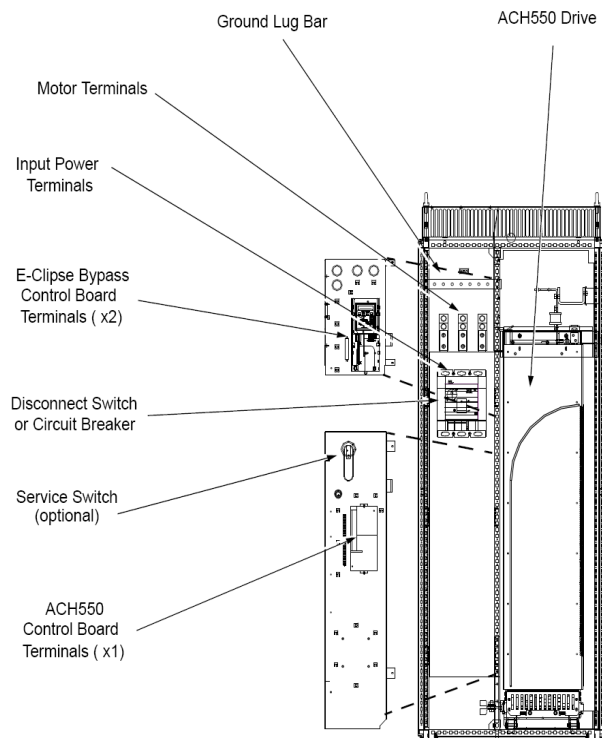
Standard Floor Mount ABB E-Clipse Bypass

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Control Terminals

The control wiring includes connections to an analog speed command signal and a start/stop relay contact for controlling the motor in the AUTO mode. There may also be connections to external run enable interlock contacts and a connection from the Motor Run contact to an external status indication circuit. For a detailed description of the control circuit functions and alternate Control Connection diagrams, refer to the *ACH550 with ABB E-Clipse bypass Users Manual.*

E-Clipse HVAC Default

ACH550 CONTROL BOARD

X1

1	Terminal for Signal Cable Shield	
2	Analog Input 1	
3	Analog Input Common	
4	10V / 10mA Reference Voltage for Potentiometer	
5	Analog Input 2	
6	Analog Input Common	

Speed Reference / Process Setpoint

Process Feedback Signal

E-CLIPSE BYPASS CONTROL BOARD

X2

1	+24VDC	
2	-24VDC	
3	Digital Input Common	
4	GND	
5	Digital Input 1 (Parameter 1601)	START/STOP
6	Digital Input 2 (Parameter 1602, 1606)	NOT SEL
7	Digital Input 3 (Parameter 1603)	START EN 1 (Safety Interlock 1)
8	Digital Input 4 (Parameter 1604, 1607)	NOT SEL
9	Digital Input 5 (Parameter 1605, 1701)	NOT SEL
10	Digital Input 6 (Fixed)	OVERRIDE 1 (Smoke Control)

Customer Auto Start

Firestat, Freezestat, High Static, Switch

X2

11	Relay Output 1 (Parameter 1401)	BYP NOT FLT
12	Default Operation: Bypass Not Faulted	11 connected to 13
13	Bypass Faulted	11 connected to 12
14	Relay Output 2 (Parameter 1404)	SYS RUNNING
15	Default Operation: System Running	14 connected to 16
16		
17	Relay Output 3 (Parameter 1407)	SYS STARTED
18	Default Operation: System Started	17 connected to 19
19		
20	Relay Output 4 (Parameter 1410)	BYPASS SEL
21	Default Operation: Bypass Selected	20 connected to 22
22		
23	Relay Output 5 (Parameter 1413)	BYPASS AUTO
24	Default Operation: Bypass in Auto	23 connected to 25
25		

Basic Control Connections for Damper Actuator Control

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Engineering Data Summary

Fuses

Drive input fuses are recommended to disconnect the drive from power in the event that a component fails in the drive's power circuitry. Recommended drive input fuse specifications are listed in the *Submittal Schedule Details* and in the *Fuse Ratings* Table. Fuse rating information is provided for customer reference.

Item	Catalog Number	Drive Input Fuse Ratings	
		Amps (600V)	Bussmann Type
1	ACH550-BCR-157A-4+F267	Class T	225A

Terminal Sizes / Cable Connection Requirements

Power and motor cable terminal sizes and connection requirements are shown in the *Submittal Schedule Details* and in the *Terminal Sizes / Cable Connection Requirements* Table. The information provided below is for connections to input power and motor cables. These connections may be made to an input circuit breaker or disconnect switch, a motor terminal block, overload relay, and/or directly to bus bars and ground lugs. The table also lists torque that should be applied when tightening terminals and spacing requirements where multiple mounting holes are provided in the bus bar.

Item	Catalog Number	Input Wiring	Output Wiring	Ground Wiring
1	ACH550-BCR-157A-4+F267	#3/0 124 in-lbs	300 MCM 301 in-lbs	2 X #3/0 250 in-lbs

Heat Dissipation Requirements

The cooling air entering the drive must be clean and free from corrosive materials. The *Submittal Schedule Details* and the *Heat Dissipation Requirements* table below give the heat dissipated into the hot air exhausted from the drives. If the drives are installed in a confined space, the heat must be removed from the area by ventilation or air conditioning equipment.

Item	Catalog Number	Watts	BTU/Hr
1	ACH550-BCR-157A-4+F267	2310	7,877

Dimensions and Weights

Dimensions and weights of the drives provided are given in the *Submittal Schedule Details* and in the *Dimensions and Weights* Table. The table also lists the applicable dimension drawings that include additional detail. Dimension drawings may be provided in the back of this submittal.

Item	Catalog Number	Height mm (in)	Width mm (in)	Depth mm (in)	Weight kg (lbs)
1	ACH550-BCR-157A-4+F267	1212 (47.7)	713 (28.1)	483 (19.0)	163 (359)

Product short Circuit Current Rating

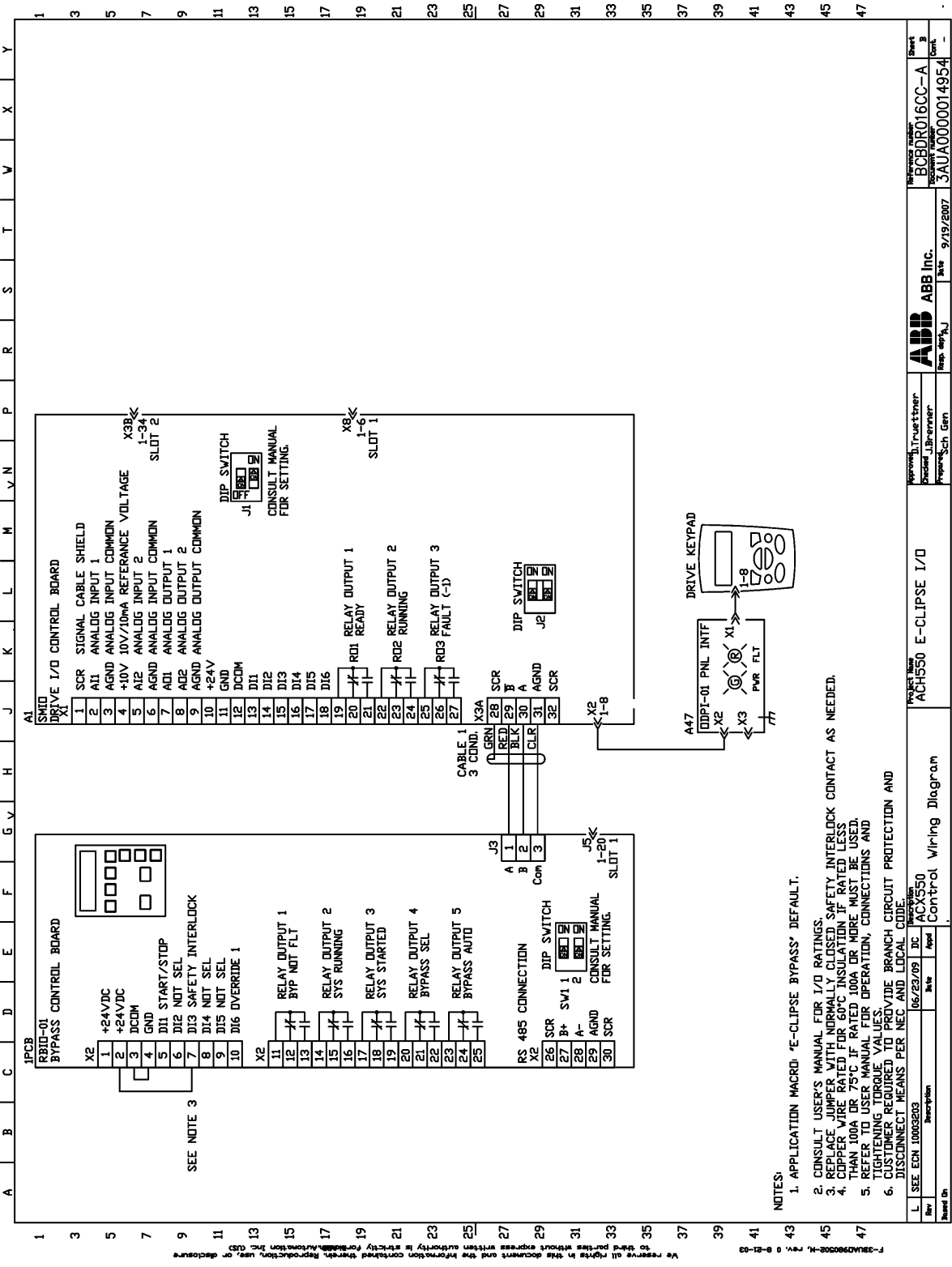Short circuit ratings shown below are as show on the device rating label.

Item	Catalog Number	Short Circuit Current Rating
1	ACH550-BCR-157A-4+F267	100 kA

Item	Part Number	Customer Designation
1	ACH550-BCR-157A-4+F267	
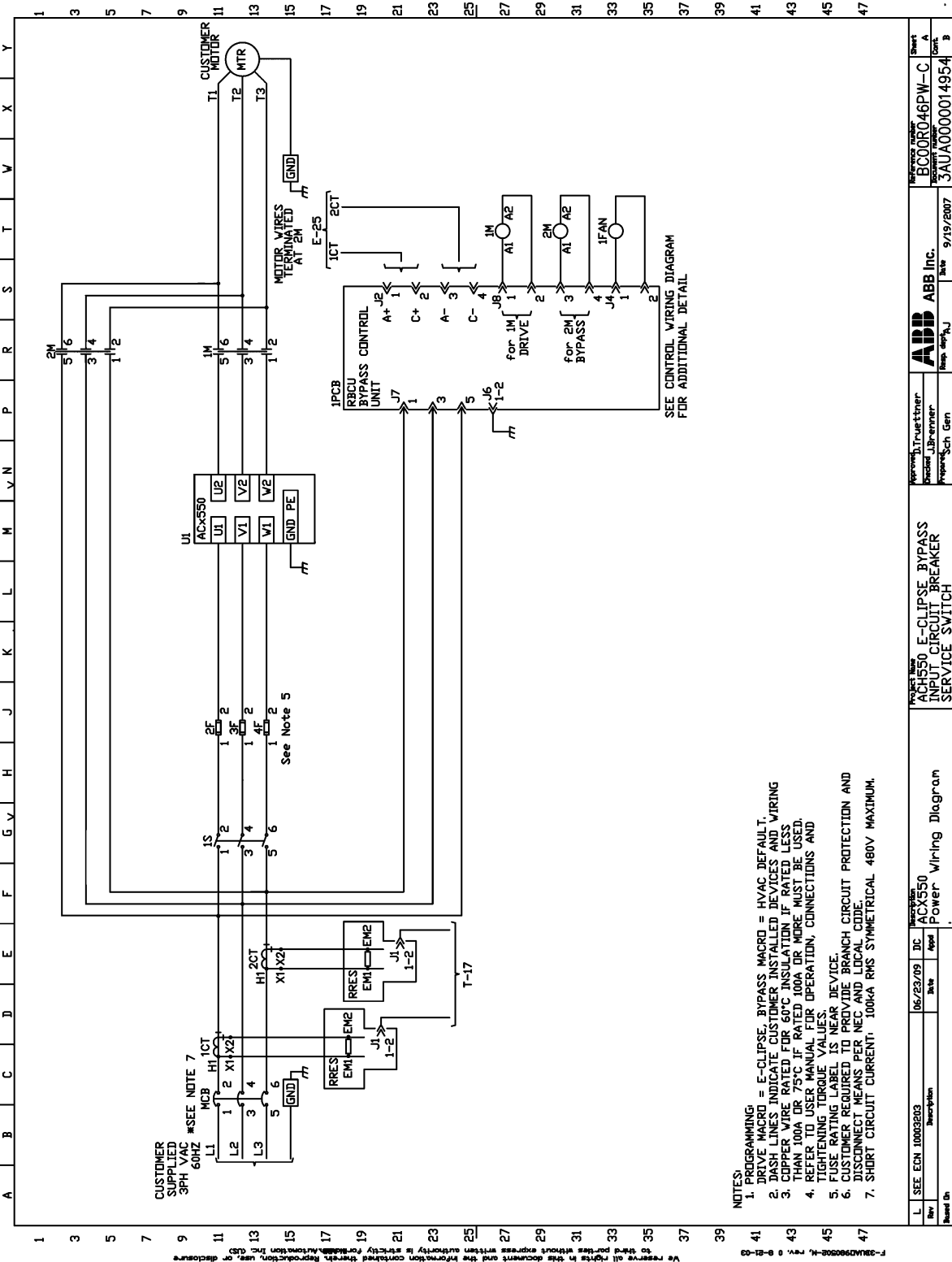
{BC00R046PW-C.png}

Item	Part Number	Customer Designation
1	ACH550-BCR-157A-4+F267	

{BCBDR016CC-A.png}

25

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Item	Part Number	Customer Designation
1	ACH550-BCR-157A-4+F267	

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